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Large spaces of matrices with bounded rank

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Introduction.

- I. Historical results.
- II. Flanders's method.
- III. Proof of the generalized Atkinson-Lloyd theorem.
- IV. Application to an invertibility preserver problem.

Introduction

\mathbb{K} denotes an arbitrary (commutative) field (possibly finite), n and p two positive integers with $n \geq p$, $M_{n,p}(\mathbb{K})$ the vector space of matrices with n rows, p columns and entries in \mathbb{K} , and $M_n(\mathbb{K}) := M_{n,n}(\mathbb{K})$.

Two linear subspaces V and W of $M_{n,p}(\mathbb{K})$ are **equivalent** when $\exists(P, Q) \in GL_n(\mathbb{K}) \times GL_p(\mathbb{K})$ such that $W = PVQ$.

The **upper rank** of a subset V of $M_{n,p}(\mathbb{K})$ is

$$\overline{\text{rk}}(V) := \max\{\text{rk } M \mid M \in V\}.$$

Problem : given an integer $r > 0$ with $r < n$ and $r < p$, classify the linear subspaces of $M_{n,p}(\mathbb{K})$ with upper rank r .

For small values of r , the solution is known (Schur: $r = 1$; Atkinson: $2 \leq r \leq 3$). For general values, no fully encompassing answer is known.

More realistic goals:

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- (i) Find the maximal dimension for a subspace with upper rank r .
 - (ii) Classify those subspaces with a dimension “close to” the maximal one.

I. Historical results

A. Maximal dimension

Theorem 1 (Flanders, 1962). *Let $r \in \llbracket 1, p - 1 \rrbracket$ and V be a linear subspace of $M_n(\mathbb{K})$ with $\overline{\text{rk}}(V) = r$. Then:*

(a) $\dim V \leq rn$;

(b) *If $\dim V = rn$ and $n > p$, then V is equivalent to*

$$\left\{ \left[C_1 \quad \cdots \quad C_r \quad [0]_{n \times (p-r)} \right] \mid C_1, \dots, C_r \in M_{n,1}(\mathbb{K}) \right\}$$

(c) *If $\dim V = rn$ and $n = p$, then V or V^T is equivalent to*

$$\left\{ \left[C_1 \quad \cdots \quad C_r \quad [0]_{n \times (n-r)} \right] \mid C_1, \dots, C_r \in M_{n,1}(\mathbb{K}) \right\}$$

The case $\#\mathbb{K} > r$:

H. Flanders, On spaces of linear transformations with bounded rank, *J. Lond. Math. Soc.* **37** (1962) 10-16.

The case $n = p$ and $r = n - 1$ for an arbitrary field (extended to affine subspaces):

J. Dieudonné, Sur une généralisation du groupe orthogonal à quatre variables, *Arch. Math.* **1** (1949) 282-287.

The more general case:

R. Meshulam, On the maximal rank in a subspace of matrices, *Quart. J. Math. Oxford (2)* **36** (1985) 225-229.

The more general case extended to affine subspaces:

C. de Seguins Pazzis, The affine preservers of non-singular matrices, *Arch. Math.* **95** (2010) 333-342.

B. Below the maximal dimension

The naive conjecture: a subspace V with upper rank r may be extended to one with the maximal dimension nr . Equivalently, if $n > p$, then the matrices of V vanish on some common $(p - r)$ -dimensional subspace of \mathbb{K}^p (if $n = p$, then this should hold for V or for V^T).

True for $r = 1$ (Schur)! False in general!

Notation 1. Given $(s, t) \in \llbracket 0, n \rrbracket \times \llbracket 0, p \rrbracket$, one defines $\mathcal{R}(s, t)$ as the set of all $n \times p$ matrices of the form

$$\begin{bmatrix} [?]_{s \times t} & [?]_{s \times (p-t)} \\ [?]_{(n-s) \times t} & [0]_{(n-s) \times (p-t)} \end{bmatrix}.$$

Note that $\overline{\text{rk}}(\mathcal{R}(s, t)) \leq s + t$, and equality holds whenever $s + t \leq p$.

In particular, if $r \geq 1$, then $\mathcal{R}(1, r - 1)$ is a counter-example to the above conjecture, with dimension

$n(r - 1) + (p - r + 1) = nr - (n - p + r - 1)$ (in particular: $nr - (r - 1)$ if $n = p$).

Atkinson and Lloyd ask: can we classify spaces V with upper rank r and

$$nr - (n - p + r - 1) \leq \dim V \leq nr \quad ?$$

Theorem 2 (Atkinson and Lloyd, 1980).

Let $r \in \llbracket 1, n - 1 \rrbracket$ et V be a linear subspace of $M_n(\mathbb{K})$ with $\overline{\text{rk}}(V) = r$.

Assume that $\#\mathbb{K} > r$ and $\dim V \geq nr - r + 1$.

Then:

- (a) *Either V is the subspace of a linear subspace W of $M_n(\mathbb{K})$ with $\overline{\text{rk}}(W) = r$ and $\dim W = nr$;*
- (b) *Or V is equivalent to $\mathcal{R}(1, r - 1)$ or $\mathcal{R}(r - 1, 1)$.*

M.D. Atkinson, S. Lloyd, Large spaces of matrices of bounded rank, *Quart. J. Math. Oxford (2)*, **31** (1980) 253-262.

The case $n > p$:

L.B. Beasley, Null spaces of spaces of matrices of bounded rank, in *Current Trends in Matrix Theory* 45-50, Elsevier, 1987.

What about “small” finite fields?

An extension of Atkinson-Lloyd to an arbitrary field was deemed problematic: counter-example for \mathbb{F}_2 : the space of all upper-triangular matrices with zero trace:

$$\left\{ \begin{bmatrix} a & c & d \\ 0 & b & e \\ 0 & 0 & a+b \end{bmatrix} \mid a, b, c, d, e \in \mathbb{F}_2 \right\}$$

fits into neither of the above categories.

And then no significant new result until:

Theorem 3 (de Seguins Pazzis, 2010). *Atkinson and Lloyd's theorem holds for an arbitrary field, except when $n = 3$, $r = 2$, $\#\mathbb{K} = 2$ and $\dim V = 5$, in which case the above counter-example is the only exception up to equivalence.*

C. de Seguins Pazzis, The classification of large spaces of matrices with bounded rank, arXiv:

<http://arxiv.org/abs/1004.0298>

Beasley's results are also successfully extended to an arbitrary field (no exception!).

II. Flanders's method

To simplify things, we take $n = p$.

A. The original method.

Let V a linear subspace of $M_n(\mathbb{K})$ with $\overline{\text{rk}}(V) = r \in \llbracket 1, n - 1 \rrbracket$. One may assume that V contains

$$J_r := \begin{bmatrix} I_r & [0]_{r \times (n-r)} \\ [0]_{(n-r) \times r} & [0]_{(n-r) \times (n-r)} \end{bmatrix}.$$

In that case, we split every matrix of V with the same block sizes:

$$M = \begin{bmatrix} A(M) & C(M) \\ B(M) & D(M) \end{bmatrix}.$$

Assume that $\#\mathbb{K} > r$ and let $M \in V$. Now, given an indeterminate t , compute the $(n - r) \times (n - r)$ matrix $P(t)$ of all $(r + 1) \times (r + 1)$ minors of $J_r + tM$ where one takes all the first r rows and columns:

→ $P(t)$ is a polynomial of t with coefficients in $M_{n-r}(\mathbb{K})$ and degree $\leq r$;

→ $P(t)$ vanishes everywhere on \mathbb{K} , therefore $P(t) = 0$;

→ Its coefficient before t^r is $D(M)$; thus

$$D(M) = 0 \quad ;$$

→ Consequently, its coefficient before t^{r-1} is $-B(M)C(M)$; thus

$$B(M)C(M) = 0.$$

From $\forall M \in V$, $B(M)C(M) = 0$, one easily proves that $\dim B(V) + \dim C(V) \leq r(n - r)$ (e.g.

$B(V) \times C(V)$ is totally isotropic for the non-degenerate quadratic form $(B, C) \mapsto \text{tr}(BC)$).

Therefore:

$$\dim V \leq \dim A(V) + \dim B(V) + \dim C(V) \leq nr.$$

Analysing the case of equality.

Assume now $\dim V = nr$. Then (rank theorem) V contains, for every invertible $P \in M_n(\mathbb{K})$,

$$M_P := \begin{bmatrix} P & [0]_{r \times (n-r)} \\ [0]_{(n-r) \times r} & [0]_{(n-r) \times (n-r)} \end{bmatrix}.$$

With the above method, one replaces J_r with M_P and finds:

$$\forall M \in V, B(M)P^{-1}C(M) = 0.$$

Then varying P yields:

$$\forall M \in V, B(M) = 0 \quad \text{or} \quad C(M) = 0.$$

One easily concludes: either $B(V) = \{0\}$ or $C(V) = \{0\}$. This yields the Flanders theorem.

B. Our new approach

Same starting point, assumptions (except on the cardinality of \mathbb{K}) and notations. Also, instead of assuming that V contains J_r , we simply assume that it contains

$$\begin{bmatrix} Q & [0]_{r \times (n-r)} \\ [0]_{(n-r) \times r} & [0]_{(n-r) \times (n-r)} \end{bmatrix}$$

for some *invertible* $Q \in M_r(\mathbb{K})$.

We take an arbitrary matrix of $M_n(\mathbb{K})$

$$M_0 = \begin{bmatrix} P & C(M_0) \\ B(M_0) & D(M_0) \end{bmatrix}.$$

We actually do not compute the matrix of minors of a general sum $M_0 + M$ with $M \in V$ (too complicated!). Rather, we consider a tower of linear subspaces of V :

$$V_3 \subset V_2 \subset V_1 \subset V.$$

where

$$\begin{cases} V_1 & := \text{Ker } A \\ V_2 & := \text{Ker } A \cap \text{Ker } B \\ V_3 & = \text{Ker } A \cap \text{Ker } B \cap \text{Ker } C. \end{cases}$$

The rank theorem shows:

$$\dim V = \dim A(V) + \dim B(V_1) + \dim C(V_2) + \dim D(V_3).$$

One then computes the matrix of all the $(r+1) \times (r+1)$ minors of $M_0 + M$ which use the r first rows and columns, for $M \in V_1$: this is

$$\begin{aligned} & \det(P)D(M_0 + M) \\ & \quad - B(M_0 + M) \text{com}(P)^T C(M_0 + M). \end{aligned}$$

This matrix is 0, and so is the one for $M = 0$.

Subtracting both equalities yields the

fundamental formula:

$$\begin{aligned} B(M) \text{com}(P)^T c(M) &= \det(P)D(M) \\ & \quad - B(M) \text{com}(P)^T c(M_0) \\ & \quad - B(M_0) \text{com}(P)^T c(M) \end{aligned}$$

As P may be chosen invertible, this yields:

$$\boxed{D(V_3) = 0.}$$

Taking the polar form of the left-hand side yields, for every $(M, N) \in V_1^2$:

$$B(M) \operatorname{com}(P)^T c(N) + B(N) \operatorname{com}(P)^T c(M) = 0.$$

In particular, for every $(M, N) \in V_1 \times V_2$:

$$B(M) \operatorname{com}(P)^T c(N) = 0.$$

In particular

$\forall (M, N) \in V_1 \times V_2$, $B(M)Q^{-1}C(N) = 0$, and therefore

$$\boxed{\dim B(V_1) + \dim C(V_2) \leq r(n - r).}$$

This yields $\dim V \leq nr$.

For the case $\dim V = nr$, the proof goes on using the above formulas ...

III. Sketch of the proof for the generalized Atkinson-Lloyd theorem.

We continue with the assumptions of the latest section. We now assume $\dim V > nr - r + 1$.

A. Step 1: showing that $B(V_1) = 0$ or $C(V_2) = \{0\}$.

We show that either there is no non-zero matrix in V of the form

$$\begin{bmatrix} [0]_{r \times n} \\ [?]_{(n-r) \times n} \end{bmatrix}$$

or there is no non-zero matrix in V of the form

$$\begin{bmatrix} [0]_{n \times r} & [?]_{n \times (n-r)} \end{bmatrix}.$$

Using the above inequalities, we find

$$\dim A(V) > r^2 - (r - 1).$$

On the other hand:

$$\forall P \in A(V), \forall (M, N) \in V_1 \times V_2,$$

$$B(M) \operatorname{com}(P)^T C(N) = 0.$$

Lemma 4. *One has $B(V_1) = \{0\}$ or $C(V_2) = \{0\}$.*

Proof. Assume the contrary holds. Then $\operatorname{span}\{\operatorname{com}(P)^T \mid P \in A(V)\}$ does not act transitively on \mathbb{K}^r . Without loss of generality, one may then assume that

$$\forall P \in A(V), \operatorname{com}(P)_{r,r} = 0.$$

This contradicts the Flanders theorem!! □

If $B(V_1) = \{0\}$, then for $W := V^T$, one has $C(W_2) \subset B(V_1)^T = \{0\}$. No generality is then lost by assuming that $C(V_2) = \{0\}$. Then $V_2 = V_3 = \{0\}$.

B. Step 2: Finding a common null-space.

We now assume $V_2 = \{0\}$. In that case, there is a linear subspace $W \subset M_{n,r}(\mathbb{K})$ and a linear map $\varphi : W \rightarrow M_{n,n-r}(\mathbb{K})$ s.t.

$$V = \left\{ \begin{bmatrix} M & \varphi(M) \end{bmatrix} \mid M \in W \right\}.$$

Note that $\text{codim } W < r - 1$.

From there, we prove two lemmas.

Lemma 5. *One has*

$$\forall N \in W, \text{Im } \varphi(N) \subset \text{Im}(N).$$

Lemma 6. *There exists $C \in M_{r,n-r}(\mathbb{K})$ s.t.*

$$\forall N \in W, \varphi(N) = NC.$$

With the last one, take $P := \begin{bmatrix} I_r & -C \\ [0]_{(n-r) \times r} & I_{n-r} \end{bmatrix}$

and check that any matrix of VP has all last $n - r$ columns equal to zero.

Proof of Lemma 5: Denote by U the space of matrices of W with 0 as last column. For $M \in U$, write

$$\begin{bmatrix} M & \varphi(M) \end{bmatrix} = \begin{bmatrix} K(M) & [?]_{(n-1) \times (n-r)} \\ [0]_{1 \times r} & \varphi_n(K(M)). \end{bmatrix}$$

Note that:

- $\text{codim } K(U) < r - 1 < n - 2$;
- if $\text{rk } K(M) = r$, then $\varphi_n(K(M)) = 0$.
- $\varphi_n : K(U) \rightarrow M_{1, n-r}(\mathbb{K})$ is linear.

We deduce that $\varphi_n = 0$ by using the following corollary of our extension of Flander's theorem to affine subspaces:

Corollary 7. *Let V' be a linear subspace of $M_{n,p}(\mathbb{K})$, with $n \geq p \geq r$, and assume that $\dim V' > rn$. Then V' is spanned by its matrices of rang $\geq r$, unless $n = p = 2$, $r = 1$ and $\#\mathbb{K} = 2$.*

Proof. If the conclusion does not hold, then take a linear hyperplane H of V' which contains every rank $\geq r$ matrices of V' , and then a parallel disjoint affine hyperplane H' , which then has dimension $\geq rn$, has upper rank $< r$ and is not a linear subspace of $M_{n,r}(\mathbb{K})$. \square

Back to the proof of Lemma 5: we now have $\varphi_n = 0$. This means that for $H = \mathbb{K}^{n-1} \times \{0\}$, $\forall M \in W, \text{Im } M \subset H \Rightarrow \text{Im } \varphi(M) \subset H$. However, H may be replaced by any linear hyperplane of \mathbb{K}^n . The conclusion follows.

Lemma 6 may be extended as some kind of linear preserver theorem:

Theorem 8 (Representation lemma). *Let m, n, p be positive integers, W be a linear subspace of $M_{m,n}(\mathbb{K})$ with $\text{codim } W \leq m - 2$, and $\varphi : W \rightarrow M_{m,p}(\mathbb{K})$ be a linear map s.t.*

$$\forall M \in W, \text{Im } \varphi(M) \subset \text{Im } M.$$

Then there exists $C \in M_{n,p}(\mathbb{K})$ s.t.

$$\varphi : M \mapsto MC.$$

Remarks 1.

- The case $W = M_{m,p}(\mathbb{K})$ is an easy exercise.
- One need only assume $p = 1$.
- The condition $\text{codim } W \leq m - 2$ is not optimal. When $\#\mathbb{K} > 2$ and $n \geq 2$, the best upper bound is $2m - 3$ (work in progress ...).

The proof is a bit too technical for a seminar talk

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IV. Application to an invertibility preserver problem.

The following theorem is the first application of the Atkinson-Lloyd theorem.

Theorem 9 (de Seguins Pazzis, 2012). *Let V be a linear subspace of $M_n(\mathbb{K})$ with codimension $\leq n - 2$, and $f : V \hookrightarrow M_n(\mathbb{K})$ be a linear embedding which is a strong invertibility preserver. Then, unless $n = 3$, $\#\mathbb{K} = 2$ and $\text{codim } V = 1$, there exists $(P, Q) \in \text{GL}_n(\mathbb{K})^2$ s.t.*

$$\forall M, f(M) = PMQ \quad \text{or} \quad \forall M, f(M) = PM^T Q$$

If \mathbb{K} is infinite or $f(V) = V$, then one need only assume that f is a weak invertibility preserver.

This is a grand generalization of the well-known Dieudonné theorem (ibid). The method is similar, with the Atkinson-Lloyd theorem as a key starting point. The above representation theorem is also a crucial point.

C. de Seguins Pazzis, The linear preservers of non-singularity in a large space of matrices, *Linear Algebra Appl.* **436-9** (2012), 3507-3530.

Remark 2. In the case $n > p$, invertibility is naturally replaced with the assumption “ $\text{rk } M = p$ ” i.e. “ M has full rank”: similar results hold (currently being written).